

## IN THE CLAIMS

Please amend the claims as follows:

1. (Currently Amended) A program storage device, readable by a machine, tangibly embodying programming instructions to perform method steps for constructing a call graph as a representation of a program, the programming instructions comprising:

selecting a program P for constructing a call graph representation thereof;

wherein the program P contains zero or more fields F<sub>F</sub> and one or more methods M<sub>M</sub>,

wherein each method M<sub>1</sub> in M<sub>M</sub> has a single body B;

wherein for each method M<sub>2</sub> in M<sub>M</sub>, the call graph representation includes a corresponding node;

wherein the call graph representation includes zero or more edges corresponding to connections between two or more of nodes;

determining identifying for each method M in M<sub>M</sub>, a set of zero or more types S<sub>M</sub> of objects that may occur therein-method M;

determining identifying for each field F in F<sub>F</sub>; a set of zero or more types S<sub>F</sub> of objects that may be stored therein-field F;

determining identifying one or more the allocation sites inside the body B of each of method M;

determining the a set of directly called methods M' inside the body B of each method M; and

determining the a set of virtually called methods M" inside the body B of each method M.

2. (Currently Amended) The program storage device according to claim 1, further comprising the programming instructions of:

adding T to the types S<sub>M</sub> for each allocation of type T that occurs in the method M.

3. (Currently Amended) The program storage device according to claim 2, further comprising the programming instructions of:

for each direct call to the methods M' in the body B of the method M performing the steps of:

adding any type that occurs in the types S<sub>M</sub> and that is a subtype of the type of a parameter of the methods M' to types S<sub>M'</sub>; and

adding any type that occurs in the types S<sub>M'</sub> and that is a subtype of the return type of the methods M' to the types S<sub>M</sub>.

4. (Currently Amended) The program storage device according to claim 3, further comprising the programming instructions of:

for each virtual call to the methods M' in the body B of the method M:

using the types S<sub>M</sub>, determine each of the methods M" that may be reached by thea dynamic dispatch:

adding any type that occurs in the types S<sub>M</sub> and that is a subtype of the type of a parameter of the methods M" to a set S<sub>M''</sub>;

adding any type that occurs in the set S<sub>M''</sub> and that is a subtype of the return type of the methods M" to the types S<sub>M</sub>.

5. (Currently Amended) The program storage device according to claim 4, further comprising the programming instructions of:

for each field F read by the method M, add any type that occurs in the types S<sub>F</sub> to the types S<sub>M</sub>; and

for each field F with the type T written by the method M, add any type that occurs in the types S<sub>M</sub> and that is a subtype of the type T to the types S<sub>F</sub>.

6. (Original) The program storage device according to claim 1, further comprising the programming instructions of:

using the call graph computed above in a compiler as a basis for performing

optimizations such as inlining.

7. (Original) The program storage device according to claim 1, further comprising the programming instructions of:

using the call graph computed above in a reporting tool to report call graph information to a user.

8. (Currently Amended) A program storage device, readable by a machine, tangibly embodying instructions to perform method steps for constructing a call graph as a representation of a program, the method comprising:

selecting a program P for constructing a call graph representation thereof;

wherein the program P contains zero or more fields F<sub>F</sub> and one or more methods M<sub>M</sub>,

wherein each method M<sub>1</sub> in M<sub>M</sub> has a single body B;

wherein for each method M<sub>2</sub> in M<sub>M</sub>, the call graph representation includes a corresponding node;

wherein the call graph representation includes zero or more edges corresponding to connections between two or more of nodes;

determining identifying for each method M in M<sub>M</sub>, a only one set of zero or more types S<sub>M</sub> of objects that may which occur therein-method M;

determining identifying for each field F in F<sub>F</sub>, a only one set of zero or more types S<sub>F</sub> of objects that may be stored therein-field F;

determining identifying one or more the allocation sites inside the body B of each of method M;

determining a set of directly called methods M' inside the body B of each method M; and

determining a set of virtually called methods M" inside the body B of each method M.

9. (Currently Amended) The program storage device according to claim 8, further comprising ~~the steps of:~~:

~~determining the set of directly called methods M' inside the body B of the method M; and~~

~~determining the set of virtually called methods M" inside the body of method M.~~

adding T to the types S<sub>M</sub> for each allocation of type T that occurs in the method M.

10. (Currently Amended) A method for constructing a call graph as a representation of a program, the method comprising:

selecting a program P for constructing a call graph representation thereof;

wherein the program P contains zero or more fields F<sub>F</sub> and one or more methods M<sub>M</sub>,

wherein each method M<sub>1</sub> in M<sub>M</sub> has a single body B;

wherein for each method M<sub>2</sub> in M<sub>M</sub>, the call graph representation includes a corresponding node;

wherein the call graph representation includes zero or more edges corresponding to connections between two or more of nodes;

determining identifying for each method M in M<sub>M</sub>, a set of zero or more types S<sub>M</sub> of objects that may occur therein method M;

determining identifying for each field F in F<sub>F</sub>, a set of zero or more types S<sub>F</sub> of objects that may be stored therein field F;

determining identifying one or more the allocation sites inside the body B of each of method M;

determining the a set of directly called methods M' inside the body B of each method M; and

determining the a set of virtually called methods M" inside the body B of each method M.

11. (Currently Amended) The method according to claim 10, further comprising:  
adding T to the types  $S_M$  for each allocation of type T that occurs in the method M.

12. (Currently Amended) The method according to claim 11, further comprising:  
for each direct call to the methods M' in the body B of the method M performing the steps of:  
adding any type that occurs in the types  $S_M$  and that is a subtype of thea type of a parameter of the methods M' to types  $S_{M'}$ ; and  
adding any type that occurs in the types  $S_{M'}$  and that is a subtype of thea return type of the methods M' to the types  $S_M$ .

13. (Currently Amended) The method according to claim 12, further comprising:  
for each virtual call to the methods M' in the body B of the method M:  
using the types  $S_M$ , determine each of the methods M" that may be reached by thea dynamic dispatch:  
adding any type that occurs in the types  $S_M$  and that is a subtype of thea type of a parameter of the methods M" to a set  $S_{M''}$ ;  
adding any type that occurs in the set  $S_{M''}$  and that is a subtype of the return type of the methods M" to the types  $S_M$ .

14. (Currently Amended) The method according to claim 13, further comprising:  
for each field F read by the method M, add any type that occurs in the types  $S_F$  to the types  $S_M$ ; and  
for each field F with the type T written by the method M, add any type that occurs in the types  $S_M$  and that is a subtype of the type T to the types  $S_F$ .

15. (Original) The method according to claim 10, further comprising the step of:  
using the call graph computed above in a compiler as a basis for performing  
optimizations such as inlining.

16. (Original) The method according to claim 10, further comprising the step of:  
using the call graph computed above in a reporting tool to report call graph  
information to a user.

17. (Cancelled) A method for constructing a scalable call graph, the method comprising:  
determining for each method M, only one set of types  $S_M$  of objects that may  
occur in method M; and  
determining for each field F, only one set of types  $S_F$  of objects that may be  
stored in field F; and  
determining the allocation sites inside the body of method M;

18. (Cancelled) The method to claim 17, further comprising the steps of:  
determining the set of directly called methods  $M'$  inside the body of method M;  
and  
determining the set of virtually called methods  $M''$  inside the body of method M.